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Dr. Livi,

Enclosed is the first draft of the interface "specification" between the TOF board and SIT that Glenn promised you at your visit.

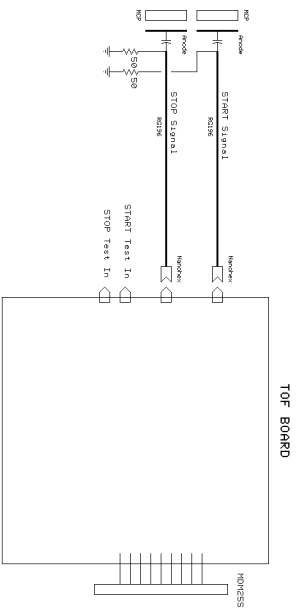
As you can see I have repeated a lot of things from my straw-man proposal at the meeting and have included some guesses at the power, size and mass as well as listing my understanding of the input and output signals involved. I have changed my mind about output format and now prefer a parallel design as being more flexible. This is reflected in the signal list. There is also a paragraph which outlines my understanding of the overall operation of the system.

Please make any and all corrections necessary.

Best regards,

Peter

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Pin	Signal
1	TOF Bit 9 (MSB)
2	TOF Bit 8
3	TOF Bit 7
4	TOF Bit 6
5	TOF Bit 5
6	TOF Bit 4
7	TOF Bit 3
8	TOF Bit 2
9	TOF Bit 1
10	TOF Bit 0 (LSB)
11	TREND?
12	USR
13	STARTR
14	STOPR
15	+12V
16	+5V
17	+3.3V
18	ROUND
19	-5V
20	-5V
21	CALGATE
22	CHLCLK
23	CHLDATA
24	spare
25	spare

TOF0-9 Parallel TOF output data

TRENDV A 5v logic signal going high when TOF0-9 are valid. May not be necessary. If can get timing from USR.

USR A 5v logic pulse indicating a STOP signal has occurred within 60ms after a START signal. Might also indicate TOF data valid. Width 0.5-1us

STARTR A 5v logic pulse indicating that the START discriminator has fired. Width 0.5-1us.

STOPR A 5v logic pulse indicating that the STOP discriminator has fired. Width 0.5-1us.

CALGATE CALCLK CHLDATA] A 5V 3-wire serial interface for calibrating the TOF. Details TBD

SIT TOF BOARD

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INPUT SIGNALS

START, STOP Capacitively coupled to MCP collection anode at HV
START rate 100-1000 Hz Start rate 100-100 kHz
STOP rate 0-50 kHz Stop rate 0-100 kHz
TOF - 1-2 to 60 ns

TEST CONNECTOR Signals from pulse generator. Negative going, 0.1V Rate 1kHz

POWER

Voltage	Current	Regulation	Power
+12	3.5mA	5%	40mW
+5	40mA	5%	200mW
+3.3	30mA	5%	100mW
-5	2mA	5%	10mW
			350mW TOTAL

SIZE

Single board, < 13cm x < 13cm Mounting TBD (5 mounting holes?)

MASS

100g total including conformal coat and connectors
excluding mounting hardware

OPERATION

System is free-running. A START signal begins measurement of time-of-flight. In all cases followed within 60 ns by a STOP, a TRIG stop pulse is generated and the digitized TOF is output in 100 ns. If there is a TRIG stop pulse, the system clears itself in 100 ns. If there is no valid stop, the system clears itself in TBD ns ready for the next START. I assume that the data is buffered internally and remains valid until the next valid stop.
Calibration cycles: ?

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